SGS-THOMSON MICROELECTRONICS

GS-R1012

120W STEP-DOWN SWITCHING REGULATOR

Type	V_i	V_o	I_o
GS-R1012	18 to 36 V	12 V	10 A

FEATURES

- Wide input voltage range (18 to 36V)
- High efficiency (90% min.)
- Parallel operation with current sharing
- Synchronization
- Remote inhibit/enable
- Remote load voltage sense
- Output short-circuit protection
- Soft-start
- PCB or chassis mountable

DESCRIPTION

The GS-R1012 is a step-down switching voltage regulator suitable to provide 12V/10A output voltage from a wide input voltage range (18 to 36V).

ABSOLUTE MAXIMUM RATINGS

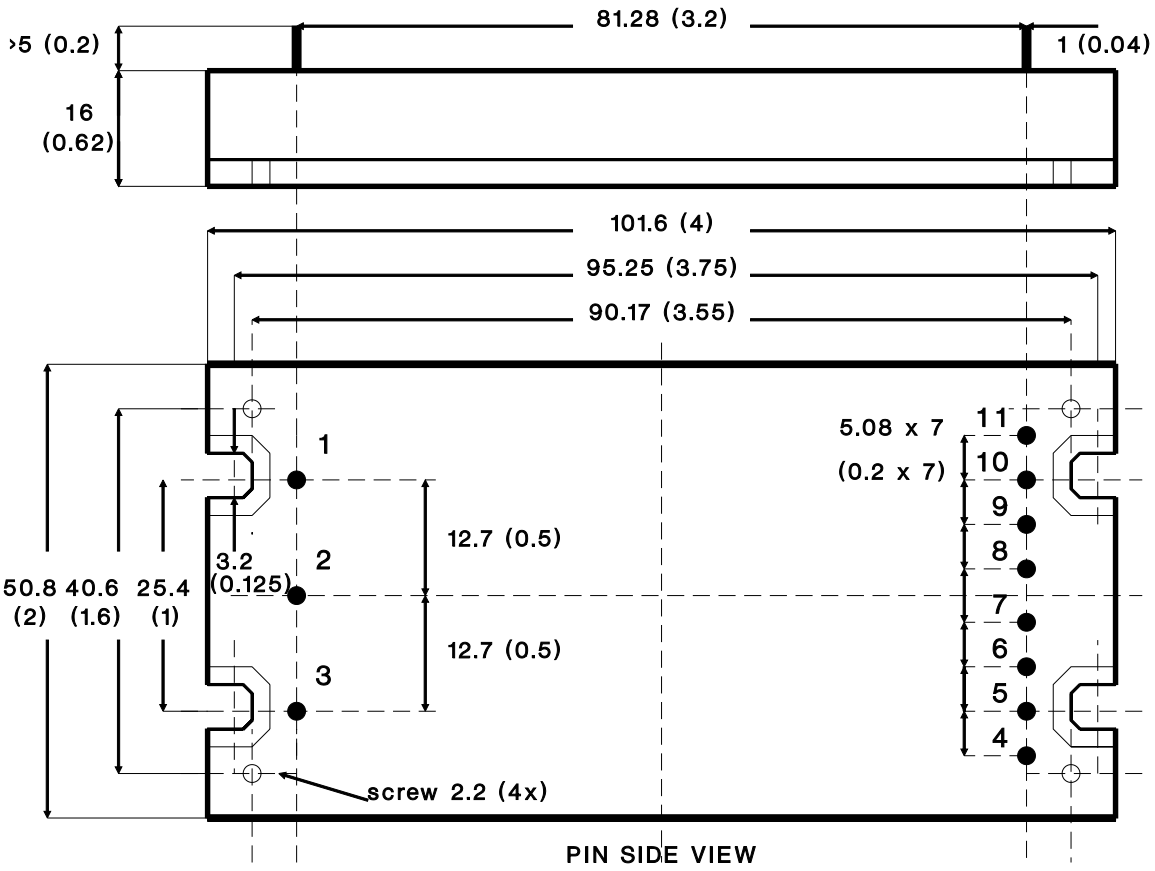
Symbol	Parameter	Value	Unit
V_i	DC Input Voltage	40	V
V_{iinh}	High Inhibit voltage	28	V
T_{stg}	Storage Temperature Range	– 20 to +105	°C
T_{cop}	Operating Case Temperature Range	0 to +75	°C

ELECTRICAL CHARACTERISTICS (T_{amb} = 25°C unless otherwise specified)

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
V_i	Input Voltage	V_O = 12V I_O = 1.5 to 10A	18	24	36	V
I_i	Input Current	V_i = 24V I_O = 10A		5,6		A
I_{ir}	Reflected Input Current	V_i = 24V I_O = 10A with external filter (C = 1000µF)		400	500	mApp
V_{ien}	Enable Input Voltage	V_i = 18 to 36V I_O = 1.5 to 10A	0		1.2	V
V_{iinh}	Inhibit Input Voltage	V_i = 18 to 36V I_O = 1.5 to 10A	2		24	V
I_{iinh}	Inhibit Input Current	V_i = 18 to 36V I_O =1.5 to 10A V_{iinh} = 5V		0.3	0.5	mA
V_O	Output Voltage	V_i = 18 to 36V I_O = 1.5 to 10A	11.4	12	12.6	V
V_{or}	Output Ripple Voltage	V_i = 24V I_O = 10A		150		mVpp
δV_{OL}	Line Regulation	V_i = 18 to 36V I_O = 10A			0.5	%
δV_{OO}	Load Regulation	V_i = 24V I_O = 1.5 to 10A			1	%
ΔV_O	Remote Sense Compensation	V_i = 24V I_O = 10A			0.5	V
I_O	Output Current*	V_i = 18 to 36V V_O = 12V	0		10	A
I_{OI}	Output Current Limiting	V_i = 18 to 36V	10.5		11.5	A
I_{osc}	Short-circuit Output Current	V_i = 24V			16	A
δI_O	Current Sharing Deviation	V_i = 24V I_O = 2 to 10A two modules in parallel			10	%
t_{ss}	Soft-start Time	V_i = 24V I_O = 10A		15		ms
tr1	Line Transient Recovery Time	V_i = 15 to 36V I_O = 5A		60		µs
tr2	Load Transient Recovery Time	V_i = 24V I_O = 1.5 to 10A		100		µs
f_S	Switching Frequency	V_i = 24V I_O = 1.5 to 10A		100		kHz
η	Efficiency	V_i = 18 to 36V I_O = 10A	90	92		%
R_{thc}	Thermal Resistance Case-to-ambient			7.5		°C/W

* Note: when output current is less than 1.5A, output ripple voltage increases due to discontinuous operation.

CONNECTION DIAGRAM AND MECHANICAL DATA



Dimensions in mm (inches).

PIN DESCRIPTION

Pin	Function	Description
1	GND Input	Return for input voltage source. Internally connected to pin 10,11.
2	Inhibit	The converter is ON (Enable) when this pin is unconnected or the voltage applied is lower than 1.2V. The converter is OFF (Inhibit) for a control voltage in the range of 2 to 24V.
3	+ Vin	DC Input voltage; recommended maximum voltage is 36V. External capacitor between pin 3 and pin 1 is mandatory; recommended value is 1000µF/50V for switching application.
4,5	+ Vout	+12V output voltage.
6	+ Sense	Senses the remote load high side. To be connected to pin 4,5 when remote sense is not used.
7	Sync	Synchronization output. See figures 1,2,3,4. Take care to leave the pin open when is not used.
8	Parallel	Parallel output. See figures 1,2,3,4. Take care to leave the pin open when is not used.
9	- Sense	Senses the remote load return. To be connected to pin 10,11 when remote sense is not used. In parallel configuration, take care to connect all -S pins together (see figures 1,2,3,4).
10,11	GND Output	Return for output current path. Internally connected to pin 1.

USER NOTES

Input Voltage

The recommended operating maximum DC input voltage is 36V inclusive of the ripple voltage. The use of an external low ESR, high ripple current capacitor located as close the module as possible is mandatory; recommended value is 1000µF/50V.

Softstart

To avoid heavy inrush current the output voltage rise time is typically 15ms in any condition of load.

Remote Sensing

The remote voltage sense compensation range is for a total drop of 500mV equally shared between the load connecting wires. It is a good practice to shield the sensing wires to avoid oscillations. See the connection diagram on figures 1, 2, 3, 4.

Parallel Operation

To increase available output regulated power, the module features the parallel connection possibility with equal current sharing and maximum deviation of 10% (two modules in parallel). See the connection diagram on figures 1, 2, 3, 4.

Module Protection

The module is protected against occasional and permanent shortcircuits of the output pins to ground, as well as against output current overload. It uses a current limiting protection circuitry, avoiding latch-up problems with certain types of loads.

Figure 1.

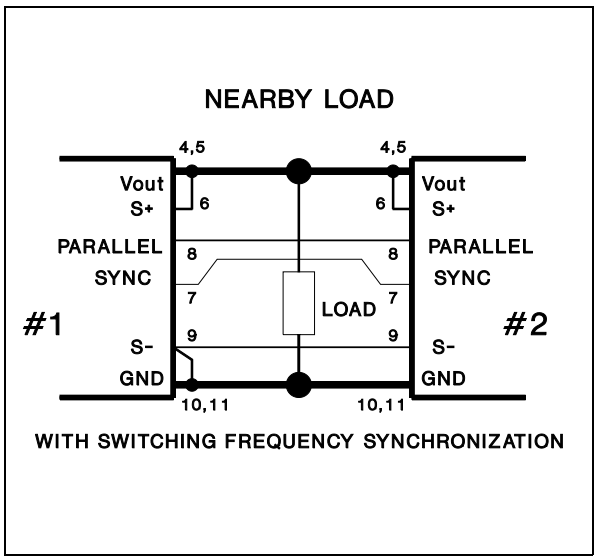


Figure 2.

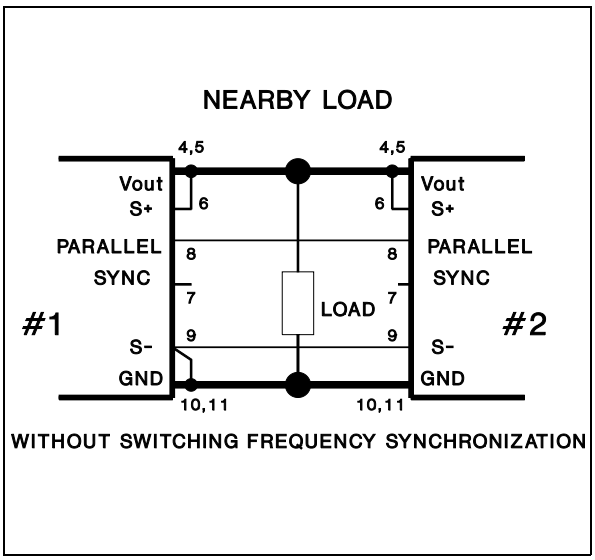


Figure 3.

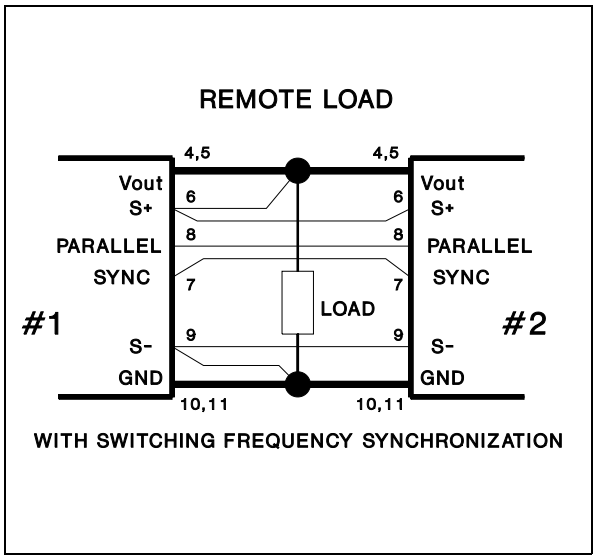
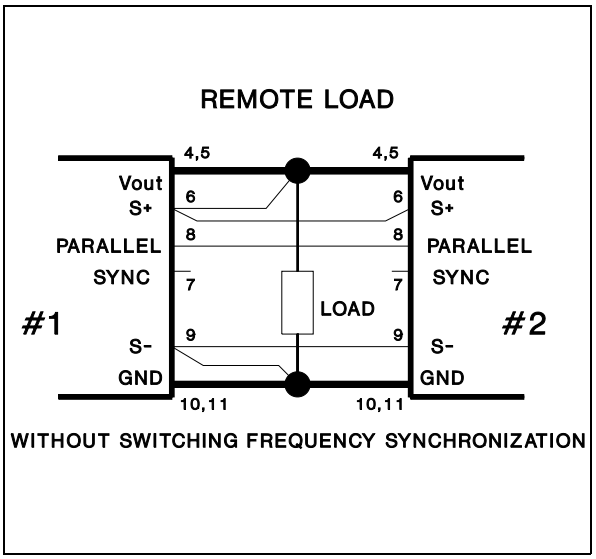


Figure 4.



Thermal characteristics: how to choose the heat-sink

Sometimes the GS-R1012 requires an external heat-sink depending both operating temperature conditions and power.

Before entering into calculations details, some basic concepts will be explained to better understand the problem.

The thermal resistance between two points is represented by their temperature difference in front of a specified dissipated power, and it is expressed in Degree Centigrade per Watt (°C/W).

For GS-R1012 the thermal resistance case to ambient is 7.5°C/W. This means that an internal power dissipation of 1W will bring the case temperature at 7.5°C above the ambient temperature.

The maximum case temperature to which the module provides 10A is 75°C (see fig. 6).

Let's suppose to have a GS-R1012 that delivers a load current of 10A at an ambient temperature of 40°C.

The dissipated power in this operating condition is about 10.4W (at typical efficiency of 92%), and the case temperature of the module will be:

$$T_{Case} = T_{Amb} + P_d \times R_{th} = 40 + 10.4 \times 7.5 = 118°C$$

This value exceeds the maximum allowed temperature and an external heat-sink must be added. To this purpose four holes (see mechanical drawing) are provided on the metal surface of the module.

To calculate this heat-sink, let's first determine what the total thermal resistance should be.

$$R_{th} = \frac{T_{CaseMAX} - T_{amb}}{P_d} = \frac{75 - 40}{10.4} = 3.37°C / W$$

This value is the resulting value of the additional heatsink thermal resistance.

Figure 5. - Efficiency vs. Output Current.

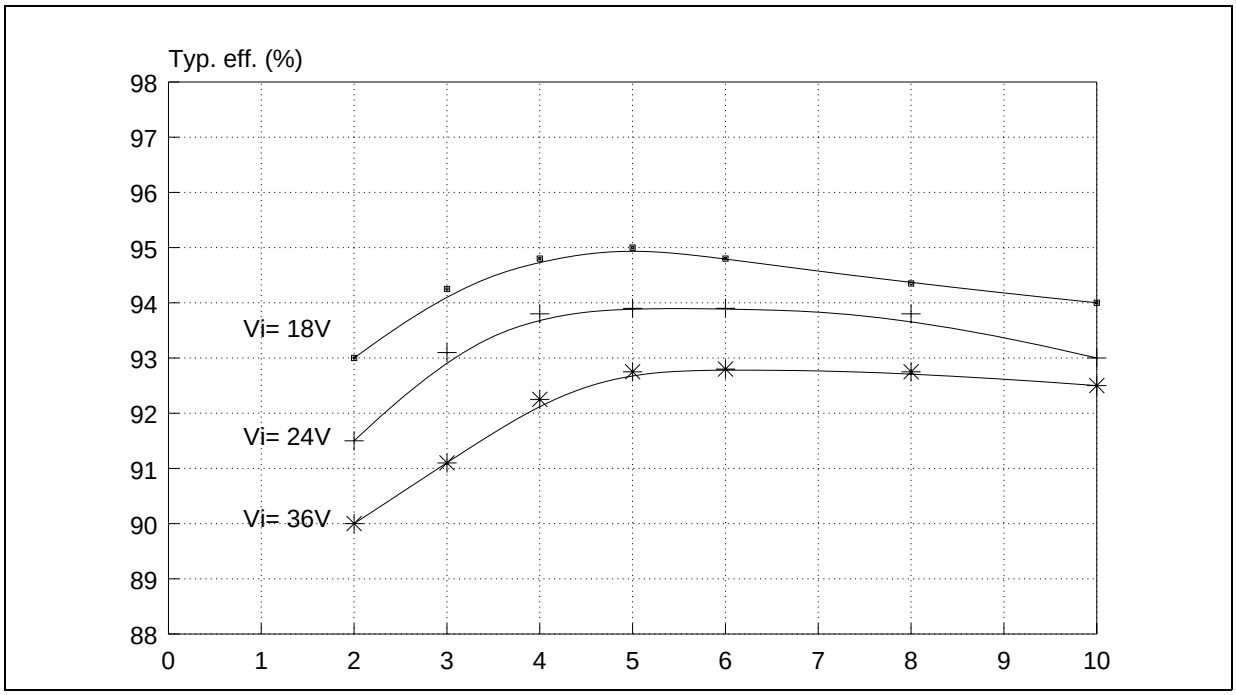
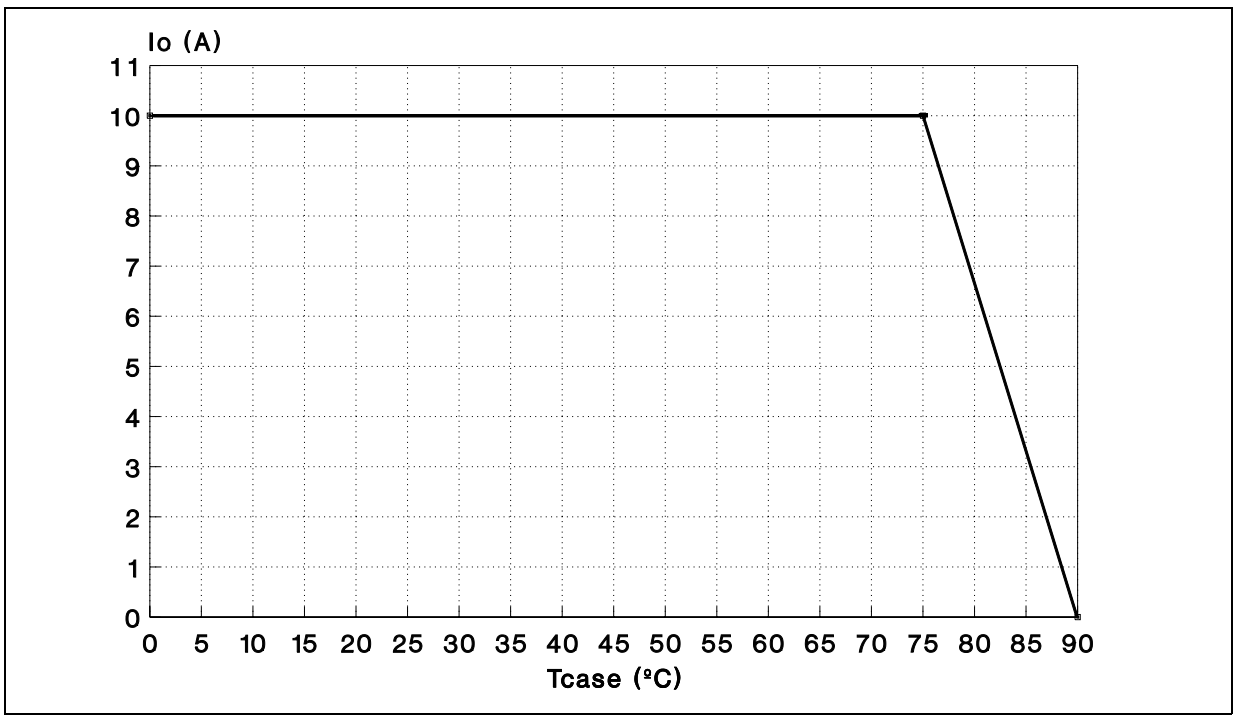


Figure 6. - Output Current vs. T case.



The following list may help the designer to select the proper commercially available heat-sink. Sometimes it can be more convenient to use a custom made heat-sink that can be experimently designed and tested.

Manufacturers	Type	Height (mm)	Rth (°C/W)
ALUTRONIC	PR139	20	3
	PR140	19	2
	PR159	20	2.5
ASSMAN	V5440	19	3
	V5805	15	2
	V5280	19	2
AAVID	60885	14	4.5
	60660	25.5	1.5
	62355	33.5	3
AUSTERLITZ	KS50	12	3
	KS100.3	15	2.5
FISCHER	SK16	25.5	1.5
	SK52	19	2
SGE BOSARI	L30	21	3
	LZ50	24	3
THERMALLOY	6155	14	4.5
	6601	14	5
	6176	24	4.5
	6320	30	1.5